

Self-Assembly

Lecture 2 Models of Self-Assembly

Models of Self-Assembly

- **The aim:** Solving the engineering problems of self-assembly: forward, backward and the yield.
 - understand the feasibility

Modelling helix formation

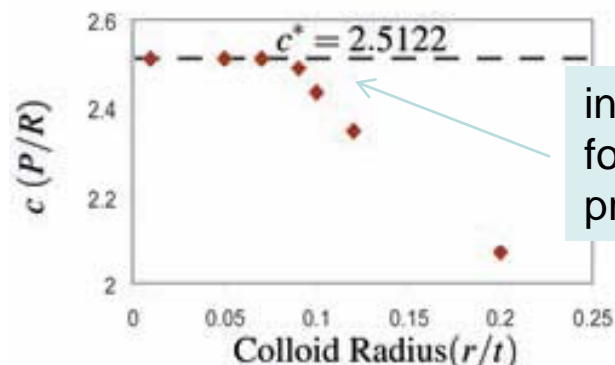
- Many long molecular chain objects self-assemble into helical shapes (DNA, α -helix of a protein).
- Why it happens?
- Is it possible to predict the helix parameters?

Modelling helix formation

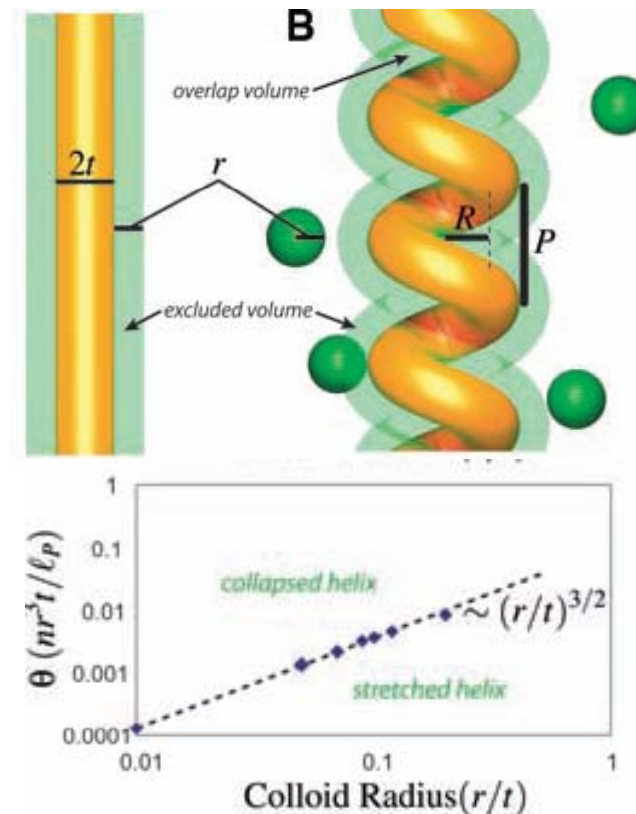
- **Model:** solid elastic rod of length L , radius t and persistence length l_p is immersed in the solution of hard spheres (radius r , concentration n)
- From a pure thermodynamic reason, the energy change upon bending the rod:

$$\Delta F \propto \frac{1}{2} L l_p \kappa^2 - n V_0$$

In a helix V_0/L is related to κ and the optimal helix parameters can be found:



indeed found in proteins



Y. Snir and R. D. Kamien, *Science* 307, 1067 (2005)

Modelling helix formation

- simple model: a bent rod on a lattice

$$\vec{m} = [m_0, m_1, \dots, m_N]$$

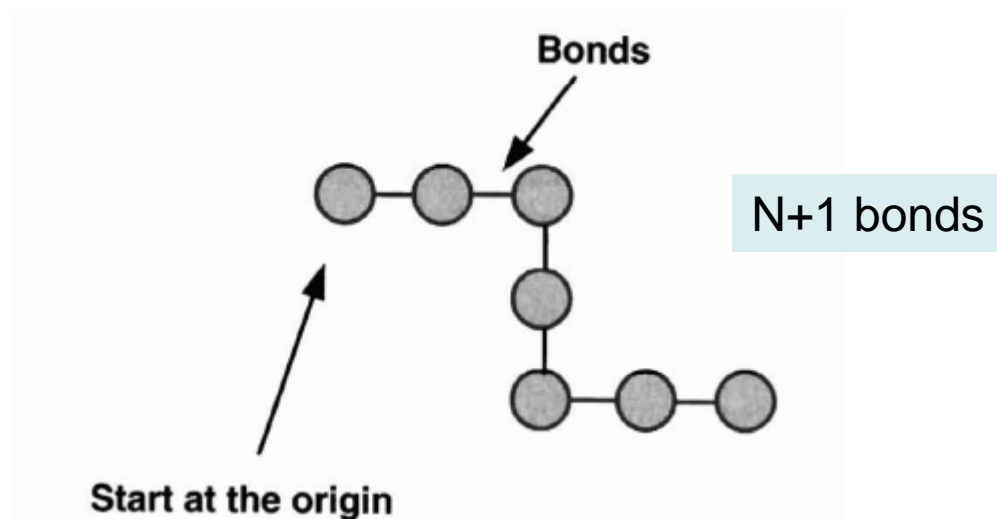
$$\text{Elastic energy} = \alpha \sum_{i=1}^N m_i^2$$

$$\text{Excluded volume energy} = \beta(V_s - V_e) = \beta V(\vec{m})$$

$$E(\vec{m}) = \alpha \sum_{i=1}^N m_i^2 - \beta V(\vec{m})$$

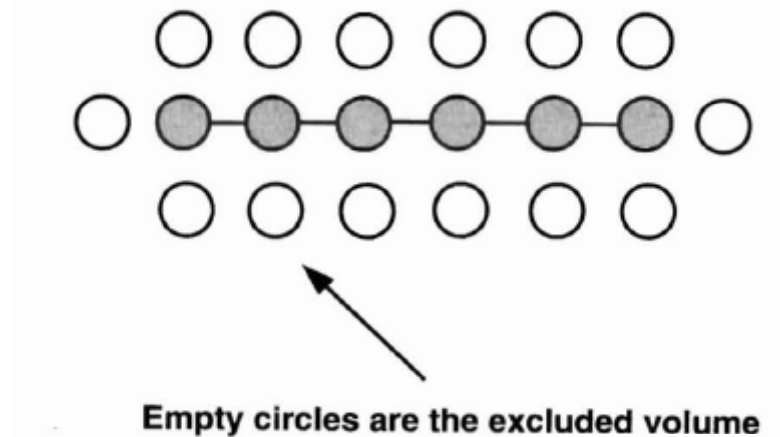
straight rod

bent rod



Modelling helix formation

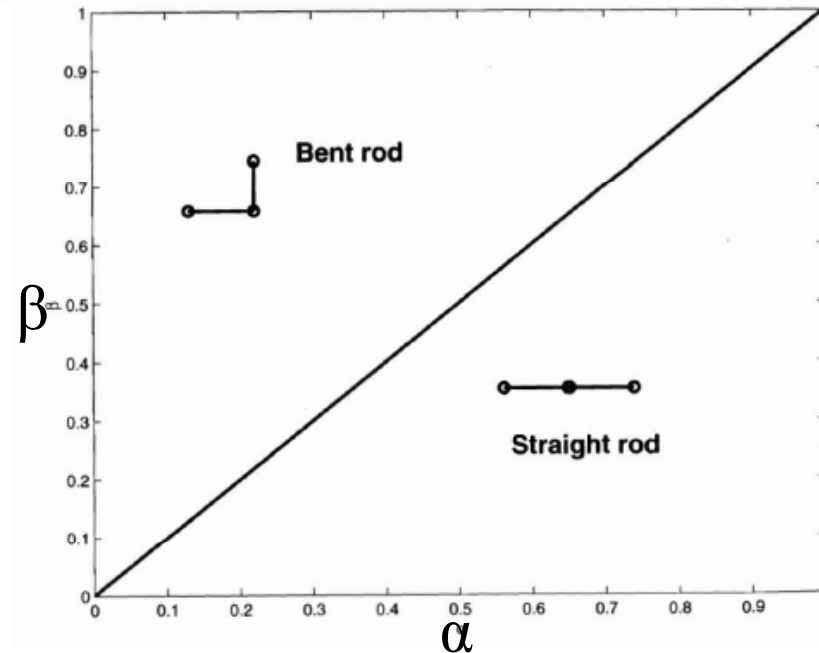
- The excluded volume in a lattice model:



- For $N=1$

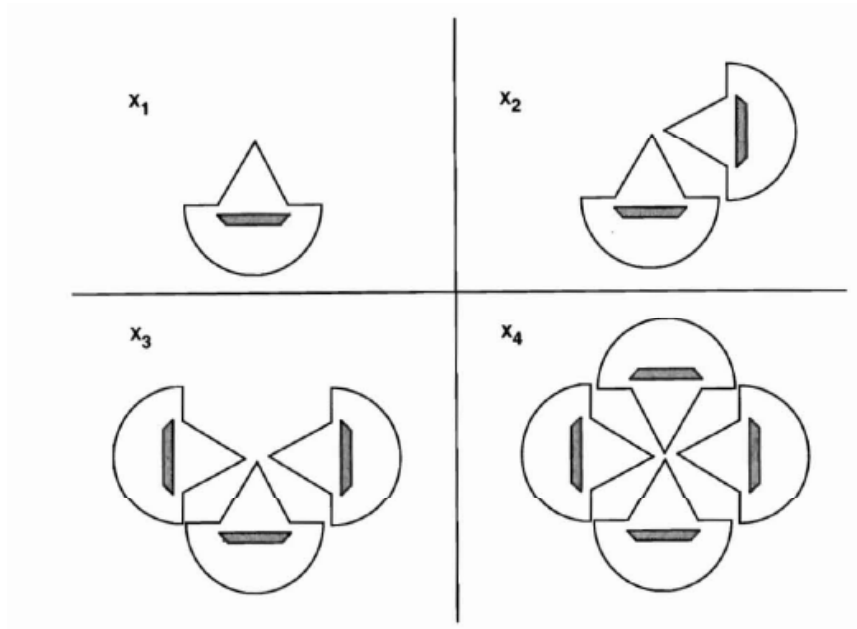
$$E[1,0] = 0$$

$$E[1,1] = \alpha - \beta$$

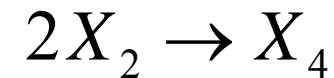
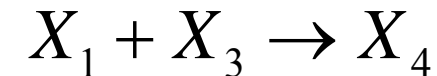
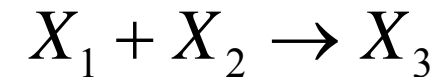
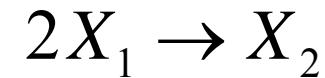


Chemical kinetics model

- In Hosokawa experiment there are 4 possible configuration of tiles:



possible reactions:



- The state of the system can be described

$$\vec{x}(t) = [x_1(t), x_2(t), x_3(t), x_4(t)]^T$$

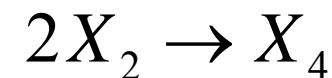
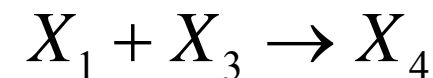
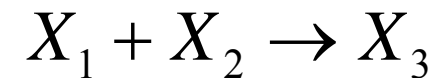
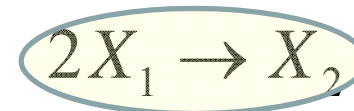
Chemical kinetics model

- The evolution of the system can be described as

$$\vec{x}(t+1) = \vec{x}(t) + AP(\vec{x}(t))$$

$$A = \begin{bmatrix} -2 & -1 & -1 & 0 \\ 1 & -1 & 0 & -2 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

possible reactions:

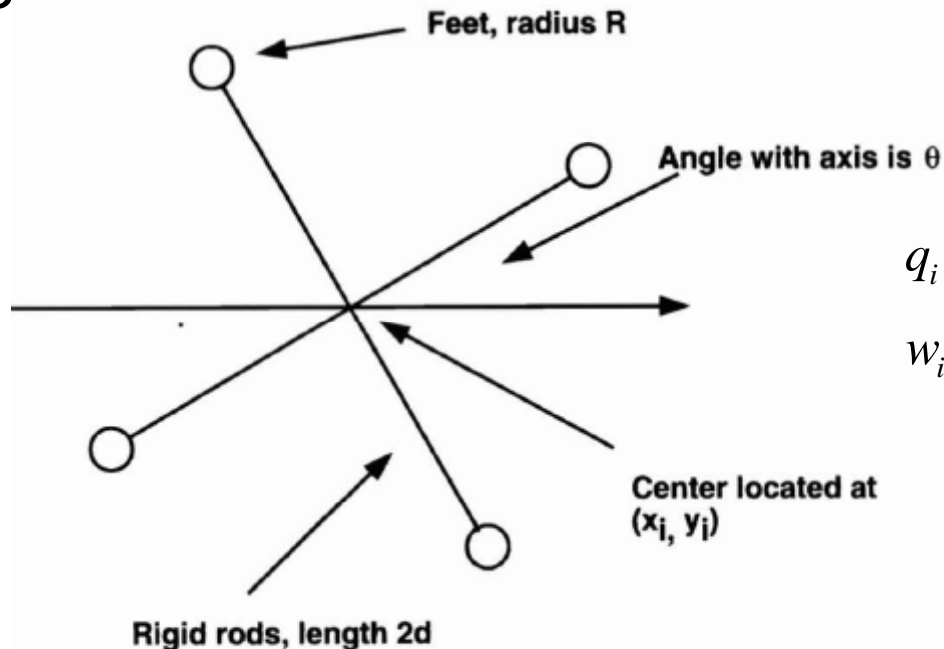


$$P[\vec{x}(t)] = \frac{1}{S^2} [P_{11}x_1^2, 2P_{12}x_1x_2, 2P_{13}x_1x_3, P_{22}x_2^2]^T$$

probability of bond formation

The Waterbug model

- The model is motivated by the capillary force driven assembly but can be reformulated for magnetic and electrostatic force as we"



$$q_i = [x_i, y_i, \theta_i]$$

$$w_i = [u_{i,j}, v_{i,j}]; u_{i,j} = x_i + d \cos \theta_i$$

- The state of the system can be described as:

$$q = [q_1, q_2, \dots, q_N]$$

The Waterbug model

- The energy can be calculated as a sum of potential energy (e.g. due to surface tension) and kinetic energy.

$$u(q_i, q_k) = - \sum_{j=1}^4 \sum_{l=1}^4 c_{ijkl} K_0(\rho \|w_{i,j} - w_{k,l}\|). \quad c_{ijkl} = 2\pi\gamma Q_{ij}Q_{kl}.$$

$$U(q) = \sum_{1 \leq i \neq k \leq n} u(q_i, q_k).$$

$$K_i = \frac{m}{2}(\dot{x}_i^2 + \dot{y}_i^2 + d^2 \dot{\theta}_i^2) \quad K = \sum_{i=1}^n K_i.$$

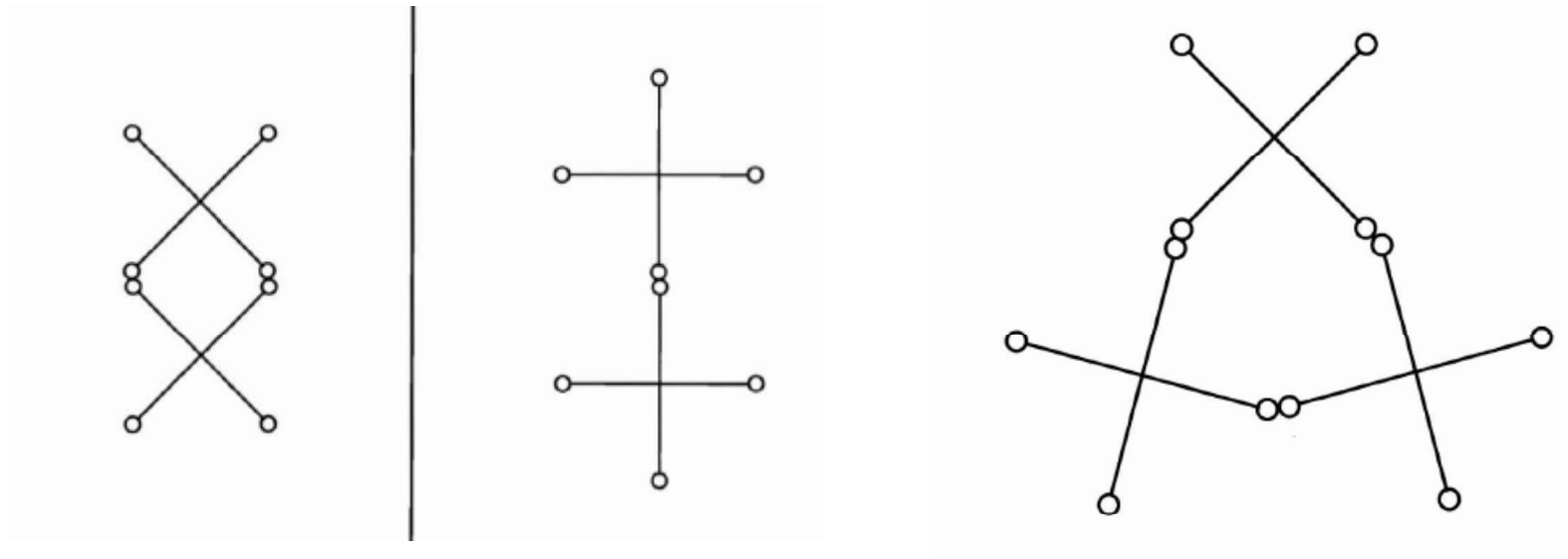
- Equating the Lagrangian to the friction forces and minimizing

$$\begin{aligned} 8m\ddot{x}_i + \sum_{k=1, k \neq i}^2 \frac{\partial}{\partial x_i} u(q_i, q_k) &= -4k_f \dot{x}_i \\ 8m\ddot{y}_i + \sum_{k=1, k \neq i}^2 \frac{\partial}{\partial y_i} u(q_i, q_k) &= -4k_f \dot{y}_i \\ 8md^2\ddot{\theta}_i + \sum_{k=1, k \neq i}^2 \frac{\partial}{\partial \theta_i} u(q_i, q_k) &= -4k_f d^2 \dot{\theta}_i. \end{aligned}$$

can be solved numerically

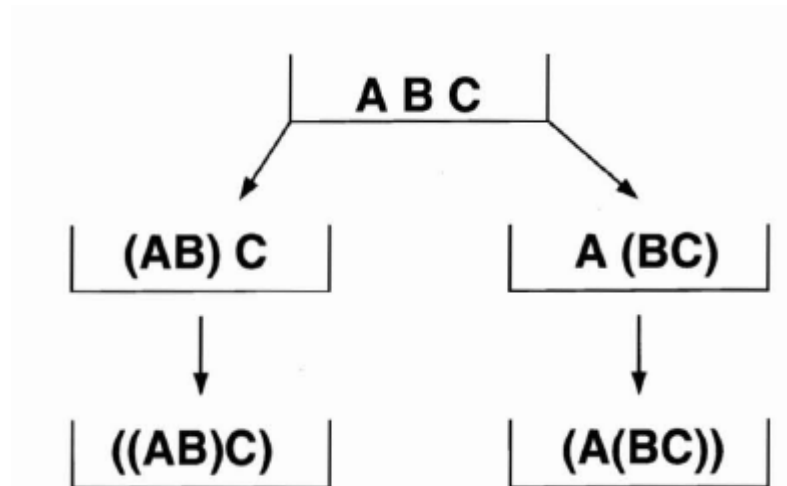
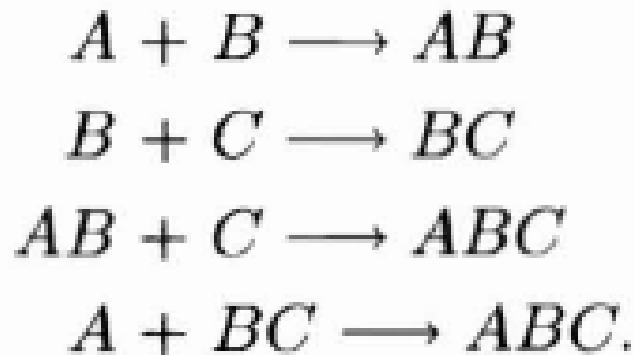
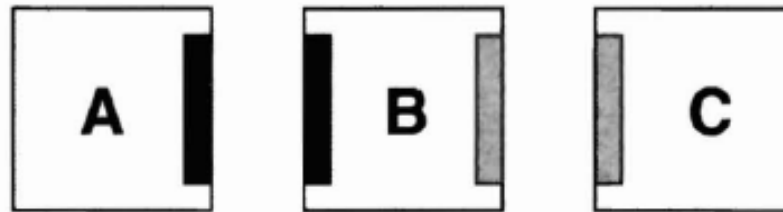
The Waterbug model

- The model can predict stability of the systems
- Demonstrate what wettability control can do to eliminate defects and to construct finite structures



Conformational switching model

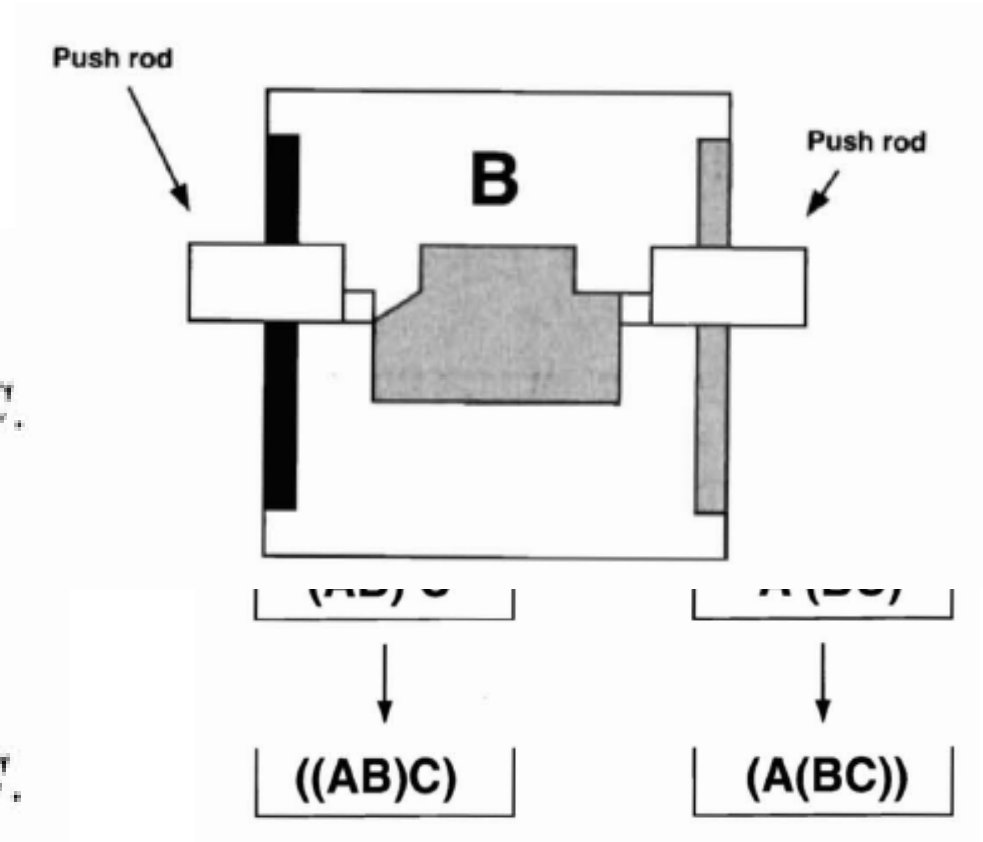
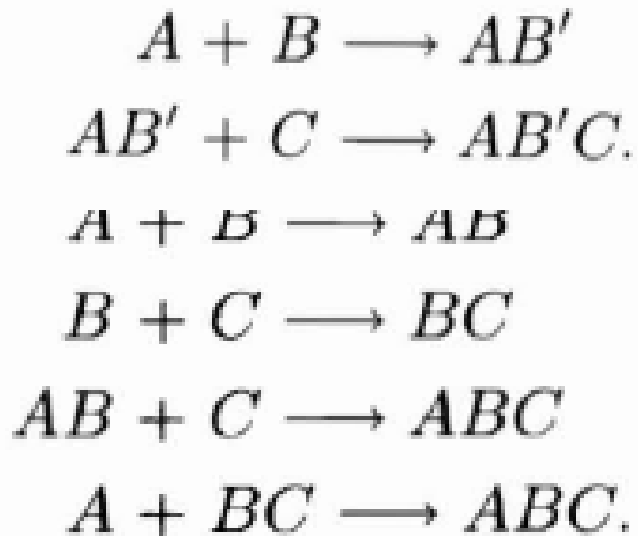
- Let's consider a system of 3 particles A,B,C that can form bonds:



- How a preferred route of self-assembly can be created?

Conformational switching model

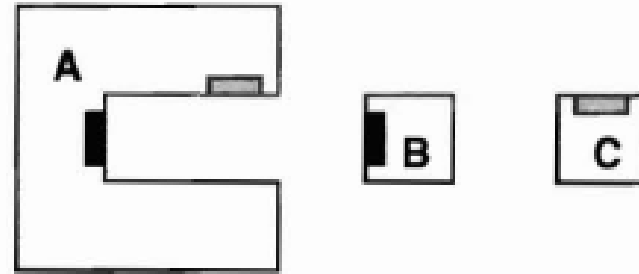
- We can introduce a conformational switch in the B-tile (“minus switch”)



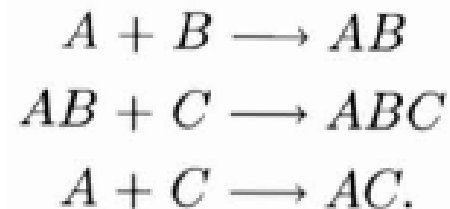
- How a preferred route of self-assembly can be created?

Conformational switching model

- Let's consider a different system:



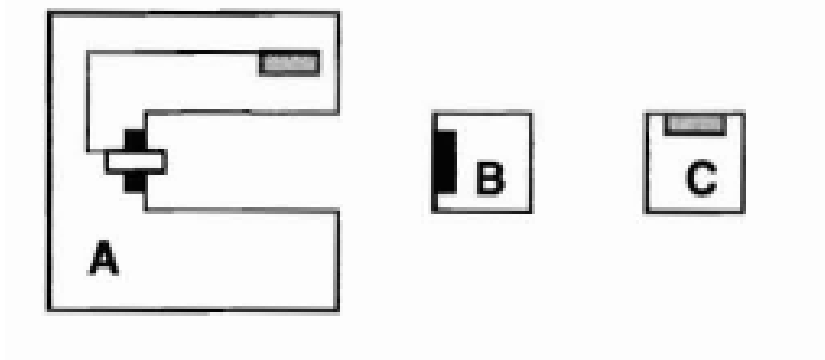
- Tile C here can block access to tile B preventing the desired structure formation



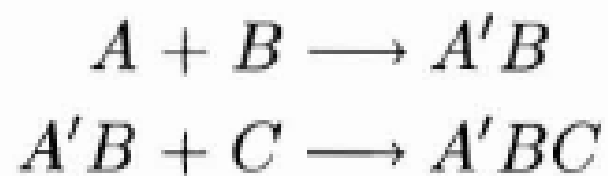
- How a preferred route of self-assembly can be created?

Conformational switching model

- To avoid it we can introduce a switch:



- Then the possible reactions are:



Conformational switching model

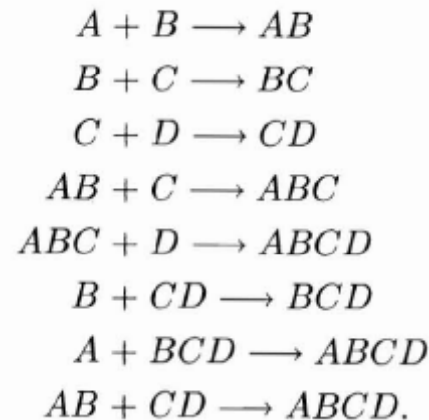
- Imagine we have to form (AB) complex in a system with a large excess of A
- The process will be very slow and within the finite time we will not get high concentration AB.
- We can introduce a different type of conformational switch in the A-tile (“plus switch”)



- This will reduce the concentration of A and increase the yield

Conformational switching model

- Now let's consider 4 particle system



- We have 5 possible assembly sequences:
(((AB)C)D); ((AB)(CD)), (A((BC)D), (A(B(CD))), (A(BC)D)
- Can we do it with a “minus device” again? – No.

Conformational switching model

- Saitou and Jakiela proved that in a general case of self-assembling automation (SA), defined as a pair of a finite set of components and a finite set of rules of the form:

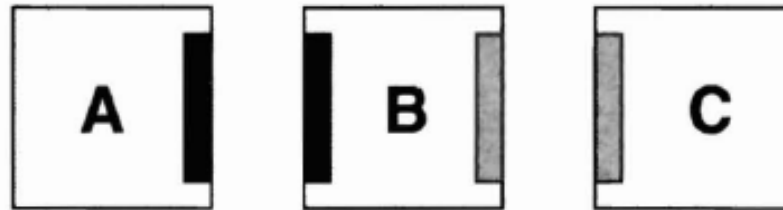
$$a^\alpha + b^\beta \rightarrow a^\gamma b^\delta.$$

$$a^\alpha b^\beta \rightarrow a^\gamma b^\delta.$$

- any assembly sequences can be encoded with just 3 conformational state per particle.

Graph Grammar (E.Klavins)

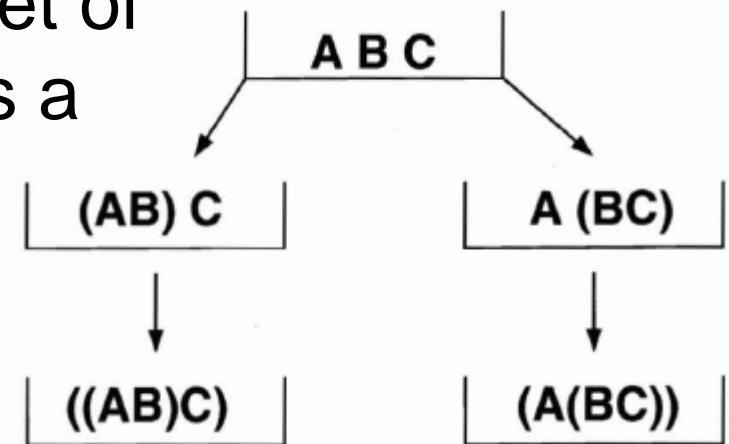
- Is it possible to incorporate conformational switching into graph approach?



- Assume we have tiles A, B, C, but now we want to form AB and CC.
AB – **unstable** complex, ABC – **stable** complex, CC – **unreachable** complex.

Graph Grammar (E.Klavins)

- Formally, **graph G** over an **alphabet Σ** is a triple $G(V, E, I)$ where **V** is set of **vertices**, **E** – set of **edges** and **I** is a labelling function
- In addition, we need to attach a set of **rules** to the graph



example of **constructive rules**

$$\begin{array}{ll} a & a \longrightarrow b - b \\ a & b \longrightarrow b - c \\ b & b \longrightarrow c - c. \end{array}$$

example of **destructive rules**

$$b - b \longrightarrow a \quad a$$

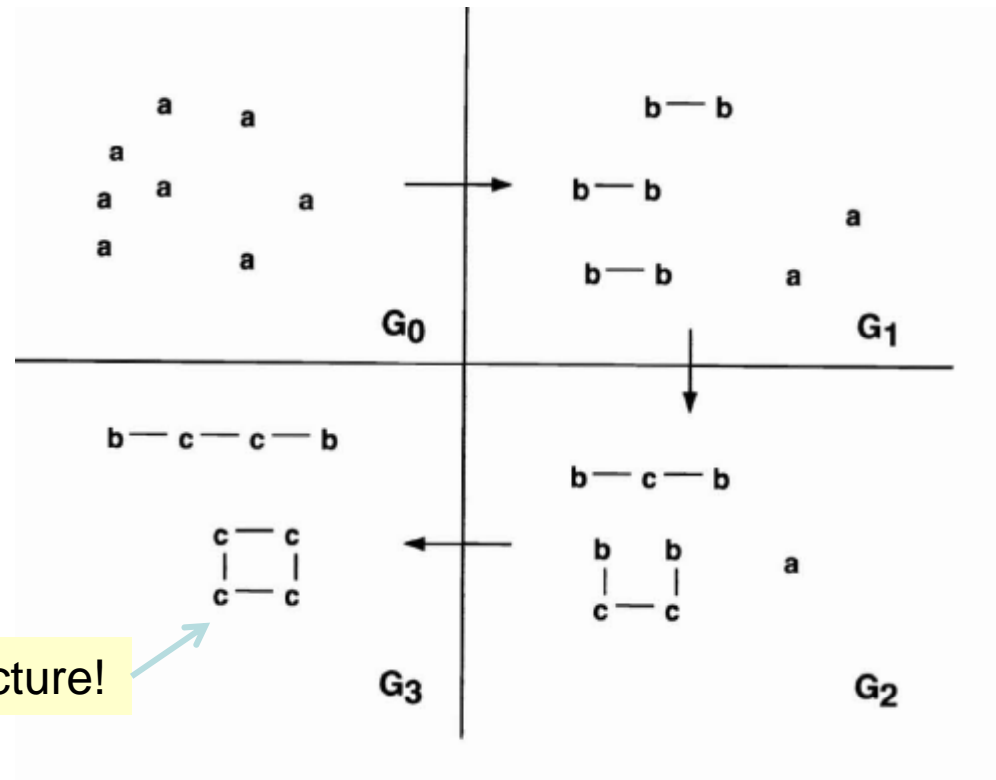
example of **relabelling rules**

$$b - b \longrightarrow a - c.$$

Graph Grammar (E.Klavins)

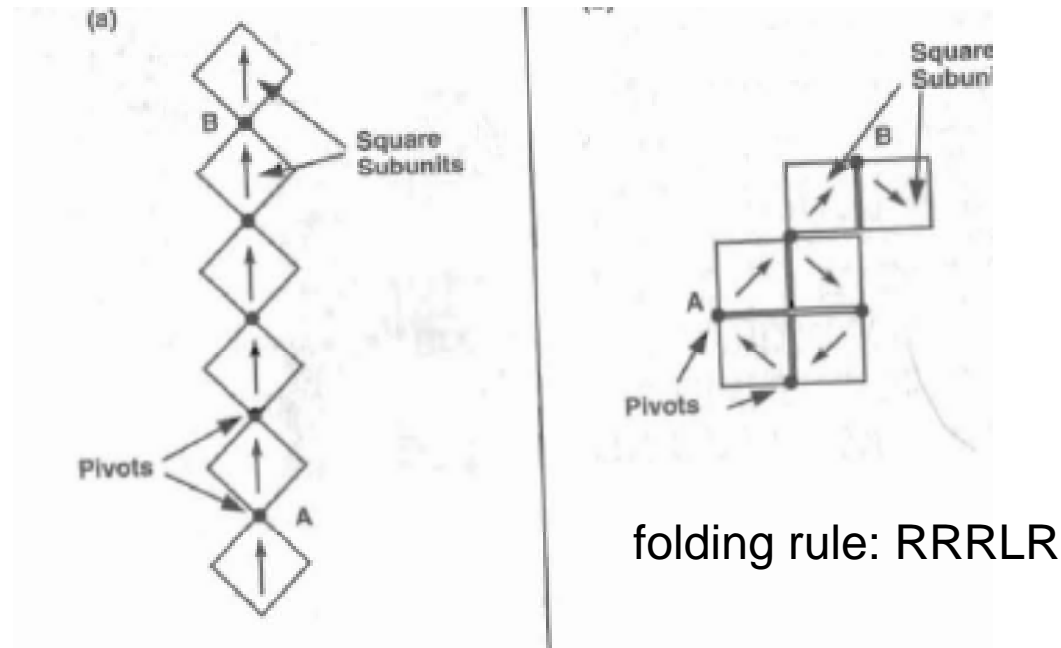
- Let's look how our rules work on a graph:

$a \quad a \longrightarrow b - b$
 $a \quad b \longrightarrow b - c$
 $b \quad b \longrightarrow c - c.$



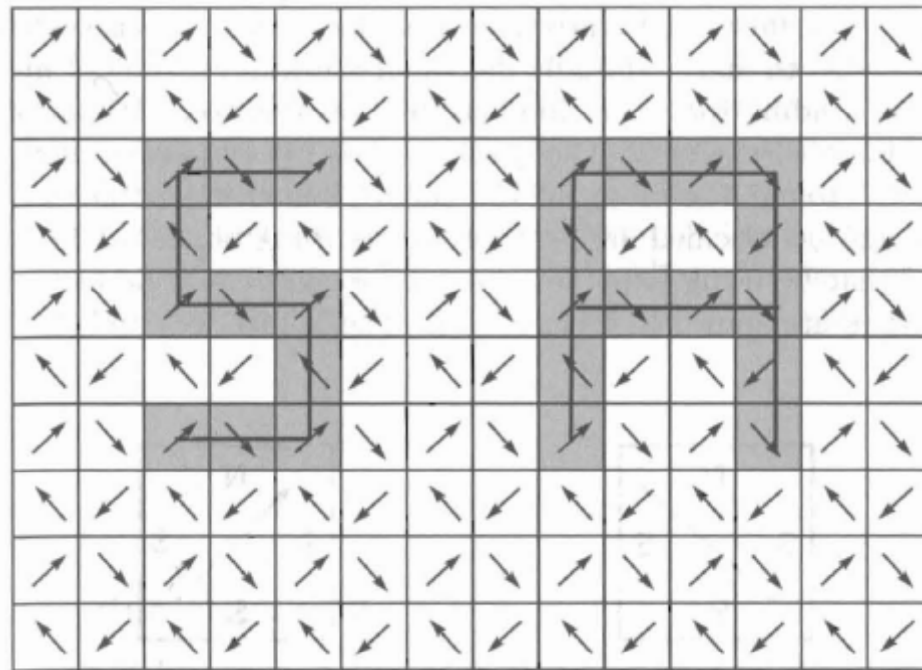
Assembly by folding

- Let's make a mechanical model of a protein:



Assembly by folding

- From this model we can define topological construction possible or impossible to reach by folding:



- impossible constructions can be made possible by increasing thickness.

Computing with tiles

- Rothemund's tiles:

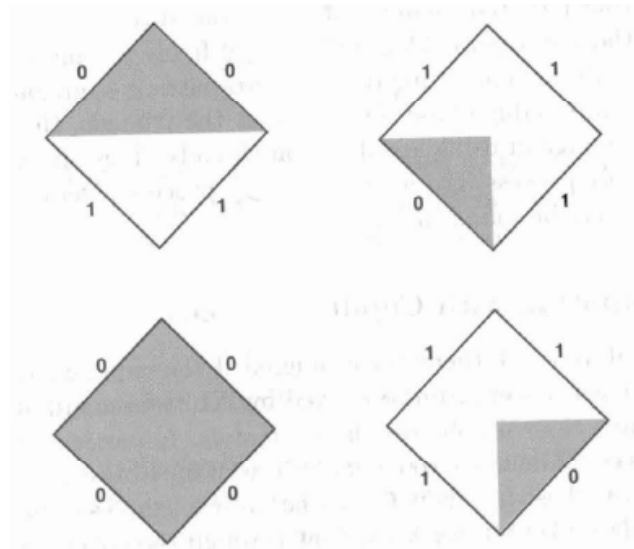
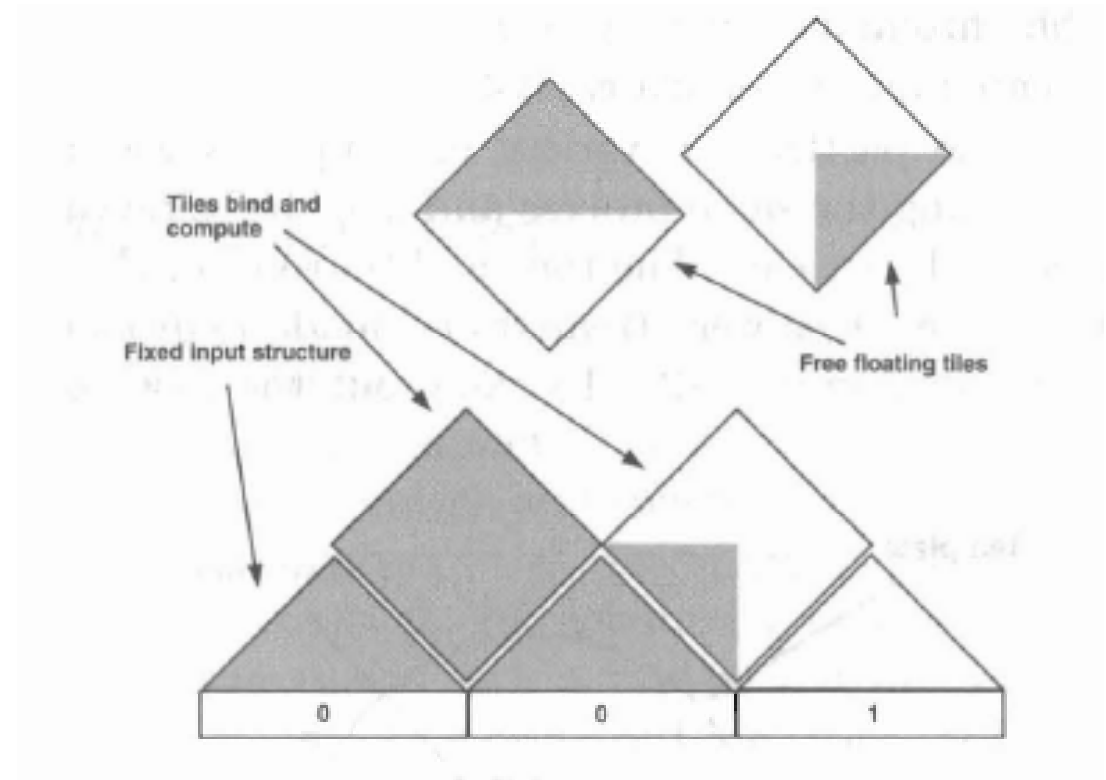


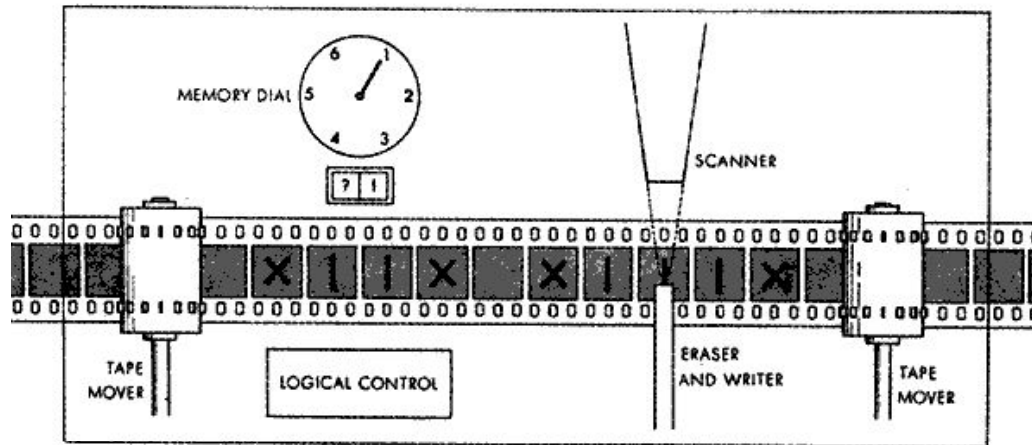
TABLE 6.1: The Logical Operation XOR

Input	Output
0 0	0
0 1	1
1 0	1
1 1	0



Tile assembly model

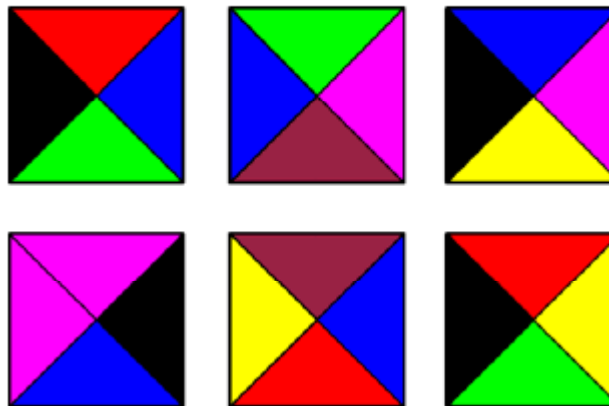
- Turing machine (introduced by Alan Turing in 1936)



- Action of Turing machine:
- A read/write head hovers above a tape where each square can either be left blank, or can contain a zero or a one.
- This read-write head can erase a symbol, write a symbol, and advance the tape one square in either direction.
- The decision is made based on the internal state of a head. The head has a finite number of states and a look-up table that dictates how it should behave once it reads the tape.
- If a special halting state where the Turing Machine stops all operation.

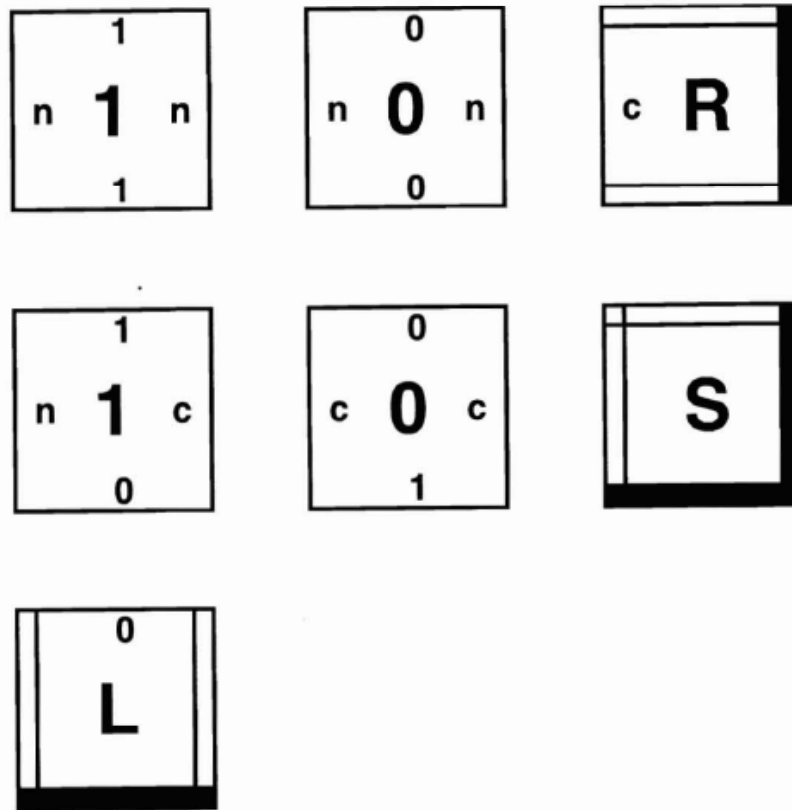
Tile assembly model

- Turing proved that this machine provides a model of computation and this model is universal.
- Other universal models of computation can be created but if they are equivalent to the **Universal Turing Machine**.
- As was shown Hao Wang in 1961, a model known as **Wang Tiles** is equivalent to the Turing Universal Machine
 - Square tiles on a square grid.
 - Tiles have four colored faces
 - Tiles must not be rotated
 - Abuttant faces have to have the same color



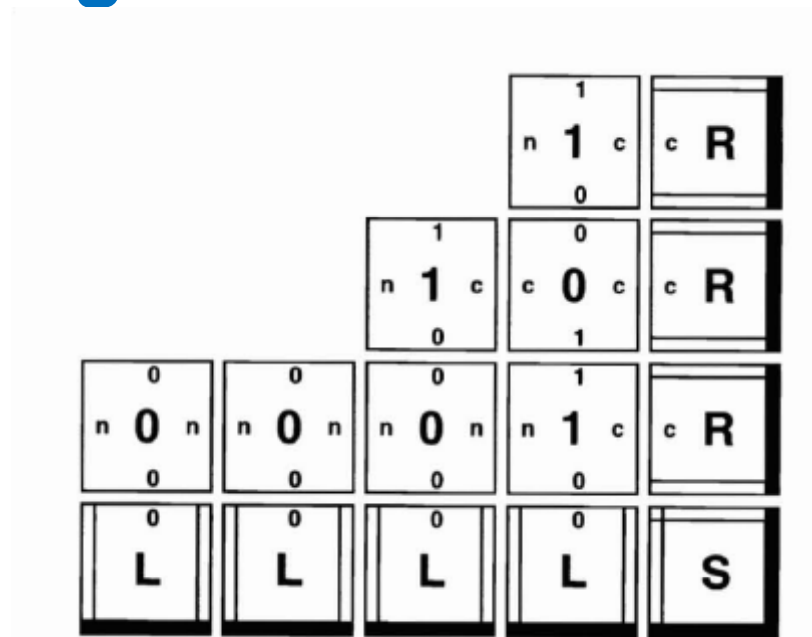
Tile assembly model

- Erik Winfree suggested to model self-assembly with tiles using instead of colours **binding domains**, assigning the **bond strength** and the **temperature**



Tile assembly model

- Temperature means that only bonds of given strength “survives”. This leads to **cooperative bonding**.



T=2

Complexity of a System

Kolmogorov's definition of complexity:

- For a given bit string the complexity can be defined as the length of the shortest computer program required to produce a string on a Universal Turing Machine*

1111111111

```
for i=1..10 write 1 end
```

1011001110

```
write 1; write 0; write 1; write 1; write 0;  
for i=1..3 write 0 end; write 0
```

- Problems with the Kolmogorov's definition:
 - Proving that given program is the shortest possible
 - Random strings are the most complex according to the definition

Complexity of systems

- Complexity can be defined in terms of tiles required to self-assemble a given bit string

1111111111

1 tile

1010101010

2 tiles

- What complexity is required to assemble a square of $N \times N$?
 - Complexity is $\sim N^2$ at $T=1$
 - but $\sim \log(N)$ at $T=2$

Problems

- (7) For a lattice model of a rod with $N=2$, compute possible configurations and sketch a phase diagram
- Home:
 - (9) Hosokawa model simulation.